

Leave Surveillance to the Top

ThinkTop® AS-Interface 29.5 - 31.6 VDC

Application

The ThinkTop® is designed to ensure optimum valve control in conjunction with Alfa Laval sanitary valves and it is compatible with most PLC systems (Programmable Logic Controllers) with AS-Interface. It is for use in food, dairy and brewery installations and in biopharmaceutical applications and can be used indoors as well as outdoors.

Working Principle

The ThinkTop® is a control head including position indication and solenoid valves. It is used to control and supervise sanitary pneumatic valves. It is mounted on top of the valve. It receives signals from a PLC to control the valve and it sends feedback signals to the PLC to indicate when the valve is in a certain position.

To configure the sensor unit to the specific valve and to the application, the user sets up the ThinkTop® either by the local keys or by using the key pad (which is ordered separately). When using the key pad it may not be necessary to remove the cover of the top unit.

Sensor System

The ThinkTop® features a "No Touch" sensor system without any mechanical sensor adjustments. A magnet is mounted on the valve stem and the magnetic field (axial) is detected by sensor chips inside the sensor unit. The measuring angle from each chip is used to locate the current position of the valve stem with an accuracy of $\pm 0.004"$ (0.1mm). Note that the distance to the magnet can be $0.2"$ (5 mm) $\pm 0.12"$ (3 mm).

Feedback Signals

The sensor system can be used for 3 feedback signals + 1 status signal = 4 feedback signals. 2 of the feedback signals can be external sensors if necessary.

The status signal is used for detection of the following:

- Set-up is in progress.
- Internal error.
- Maintenance is required (based on time and/or the self adjustment program).

The LEDs are constantly indicating the status of the unit: valve position, solenoid activated, setup and local fault indication, maintenance and seat-lift.



ThinkTop®

Standard Design

The ThinkTop® has a simple, modular and robust design which ensures a quick and easy assembly/disassembly. It consists of a base containing a sensor unit with LEDs, an activator stem, terminals for internal electrical connection, solenoid valves and a shell. See also Fig. 2 "Basic Design". It is prepared for upgrading and components are interchangeable. The design is hygienic and easy to clean.

Features

Tolerance Programmes

Individual tolerance programs for all Alfa Laval sanitary valve types are part of the ThinkTop® concept ensuring correct feedback to the PLC for open and closed valve position. If the function is disabled, the tolerance band will be $\pm 0.2''$ (5 mm).

Self Adjustment (SSV/SSV Aseptic valves only)

The self adjustment feature is an exceptional aspect of the ThinkTop® design. A program can be activated to allow an adjustment of the tolerance band if the seals in the valve are being compressed or are worn. When the tolerance band of the unit has been adjusted $0.12''$ (3 mm), an alert warning will appear in the form of a status signal and a flashing maintenance LED. After a $0.2''$ (5 mm) adjustment, an alarm warning signals the following: loss of feedback, status signal, a steady maintenance light, and indicates the minimum seal remaining before replacement is required.

Built-in Maintenance Monitor

The unit can be preset to indicate when the time for maintenance of the valve has been reached. A status signal and flashing maintenance LED can be programmed to return after 3, 6, 9 or 12 months or more.

Other Features

Another very important fact is that the setup is kept until programmed, even during failure in the power supply.

The accurate sensor system enables indication of seat-lift to be integrated in the top unit.

Materials

Plastic parts:	Nylon PA 6. Reinforced.
Steel parts:	Stainless steel AISI 304 and 316.
Seals:	Nitrile (NBR). EPDM rubber for SMP-EC activator stem.

Technical Data

Sensor System:

Sensor accuracy:	$\pm 0.004''$ (0.1 mm)
Distance to magnet:	$0.2'' \pm 0.12''$ (5 ± 3 mm)
Stroke length:	$0.004'' - 3.15''$ (0.1-80 mm)

Electrical connection

Direct cable gland entry (hard wired)
PG11 0.15" - 0.39" (4-10 mm).

Terminals

The terminal row of the sensor unit is equipped with screw terminals for both internal as well as external cables and wires. The terminals are suitable for wires up to 0.75 mm^2 (AWG 20).

Power Supply - DC

The power supply to the complete unit is taken from the AS-Interface. The unit is reverse polarity protected.

Supply voltage:	29.5 - 31.6 VDC
Supply current:	Max. 45 mA (for sensor unit alone, excluding current to the solenoids and the external proximity switches).

The fulfilling of the UL requirements in UL508 requires that the unit is supplied by an isolating source complying with the requirements for class 2 power units (UL1310) or class 2 and 3 transformers (UL1585).

Feedback Signals

Signals transmitted over the AS-Interface BUS to the AS-Interface master PLC.

External Sensors

The external sensors are used for seat-lift supervision (upper seat-lift) when seat-lift cannot be internally detected. The sensors get their supply voltage from the top unit. They connect directly to the terminal strip on the sensor unit. If the actual setup is set for internal seat-lift (lower seat-lift), the corresponding external signal is not used, otherwise the external signal logically controls the corresponding feedback to the PLC (Programmable Logic Controller).

Supply voltage:	As specified for the AS-Interface (typical 24 VDC)
Supply current:	Max. 15 mA per sensor.
Type of sensor, DC **):	Only 3-wire sensor PNP.

Default slave address: 0

I/O code: 7 (4 bit bi-directional)

I/D code: F (slave without profile)

P = F.7.

ASi-bus bit assignment

For the AS-Interface version, the following bit assignment will be used:

Input bit 0	- Feedback #1 Closed position:
Output bit 0	- Not connected
Input bit 1	- Feedback #2 Open position:
Output bit 1	- Solenoid valve 1
Input bit 2	- Feedback #3-4 Seat 1 or 2 position:
Output bit 2	- Solenoid valve 2
Input bit 3	- Feedback #5 Status:
Output bit 3	- Solenoid valve 3

**) Consult Alfa Laval to obtain correct sensor

Solenoid valves:

Up to 3 solenoid valves in each unit.

Type3/2 or 5/2 valve (only possible with one 5/2 valve).
 Air supply43.5 - 130.5 PSI (3-9 bar)
 Filtered air, max. particles or dirt0.0004" (0.01 mm)
 Max. oil content1.0 ppm.
 Max. water content0.0165 lb/lb air
 Throughput0.98" (2.5 mm) diameter
 Air restriction (throttle function) air inlet/outlet. Manual hold override.

 External air tube connection1/4" or 6 mm diameter
 Nominal voltage24 VDC.
 Nominal power1.0 W.

Environment/Approvals

Temperature		
Working:	-4° F to 185° F (-20° C to +85° C)	IEC 68-2-1/2
Storage:	-40° F to 185° F (-40° C to +85° C)	IEC 68-2-1/2
Temperature change:	-13° F to 158° F (-25° C to +70° C)	IEC 68-2-14
Vibration	10-55 Hz, 0.03" (0.7 mm) 55-500 Hz, 10g 3*30 min, 1 octave/minute	IEC 68-2-6
Drop test		IEC 68-2-32
Humidity		
Constant humidity:	104° F (+40° C), 21 days, 93% RH	IEC68-2-3
Cyclic humidity:	77° F/131° F (+25° C/+55° C) 12 cycles	IEC 68-2-30
(working)	93% R.H.	
Protection class	IP67	IEC 529
Input treshold		
Voltage/current:	Type 1 input requirements	EN 61131-2
Solenoid signals		
Insulation Voltage	(1000 + 2*117) VAC rms/1minute	EN 61131-2
EMC Directive	89/336/EEC	EN 50081-1, EN 50082-2 KA 2791.30 Tetra Pak Corporate Standard
UL Approval	ThinkTop sensor unit	UL508 - E203255 Project # 99NK20566



AS-Interface Standard Specification Overview (EN50295)

Medium

Unshielded two-wire cable for data and energy (30 V DC/typical up to 8A for the bus).

Length of bus cable

100 m max. (300 m with repeaters).

Number of slaves

31 maximum (each slave has its own address).

Number of participants

Up to 4 sensors and 4 actuators per slave (maximum 124, bi-directional = maximum 248 binary participants).

Addresses

Each slave has a unique address. The address is set by the master or by a "handheld" programmer.

Messages

The master transmits to each single address in turn with immediate response from each slave.

Bit-rate

4 bits (net) per slave and message.

Cycle time with 31 slaves

5 ms.

Error detection

Incorrect messages are reliably identified and repeated.

Device-interface

4 configurable data ports (as inputs or outputs or bidirectional) plus 4 parameter outputs and 2 control outputs (strobe).

Process data in the master

Cyclic polling of all participants.

Cyclic transmission of data to the host or to the slaves respectively.

Master services

Initiation of the network.

Identification of participants.

A cyclic setting of parameter values to the slaves.

Diagnosis of bus and AS-Interface slaves.

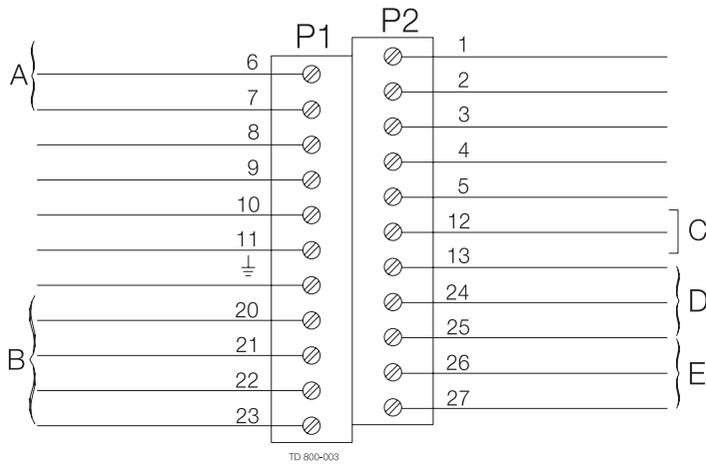
Error messages to the host.

Setting of addresses in replaced slaves.

Signal Coding

AS-Interface uses a master code in which a negative \sin^2 pulse represents a falling edge and a positive \sin^2 pulse represents a rising edge. This neutralizes RFI effects and allows unscreened two-wire cable to carry both power and data reliably.

Electrical connection, internal

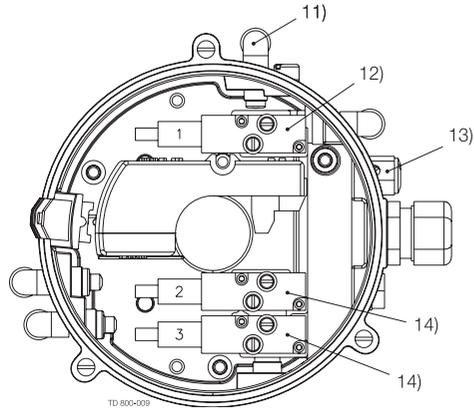
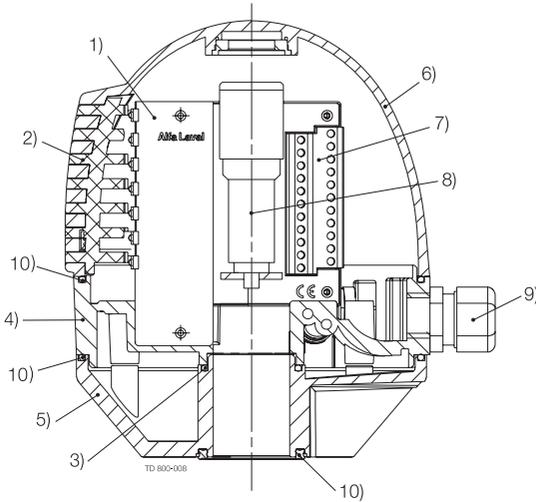


- A. Bus connection
- B. Internal connections to solenoid 1-3 **)
- C. PWM Jumper **)
- D. Incoming signals from external sensors
- E. Supply to external sensors

6. ASI P Brown (+)	1. N/C
7. ASI N Blue (-)	2. N/C
8. N/C	3. N/C
9. N/C	4. N/C
10. N/C	5. N/C
11. N/C	12. PWM Jumper
Earth	13. PWM Jumper
20. Solenoid common brown	24. Seat-lift 1 *)
21. Solenoid 1, blue	25. Seat-lift 2 *)
22. Solenoid 2, blue	26. Supply + *)
23. Solenoid 3, blue	27. Supply - *)

*) **Note!** Terminals 24, 25, 26 and 27 can be used for external seat-lift sensors as well as for any digital input. Always use an external PNP sensor. 2 external signals can be connected, they are associated with feedback signal 3 (seatlift 1) and 4 (seatlift 2). External sensor must always be a 8-30 VDC PNP 3 wire sensor. Connect (-) common on terminal 27, and (+) common on terminal 26. The signals from the external sensors are associated as follows: sensor signal on terminal 24 (seatlift 1) associated with feedback 3 (seatlift 1), and sensor signal on terminal 25 (seatlift 2) associated with feedback 4 (seatlift 2).

***) **Note!** Jumper present = PWM. (Internal connections: Terminals for connection of the solenoids mounted internally in the control head. The number of solenoids actually mounted in the control head could be 0 - 3. The signals are taken directly from the terminal row.)



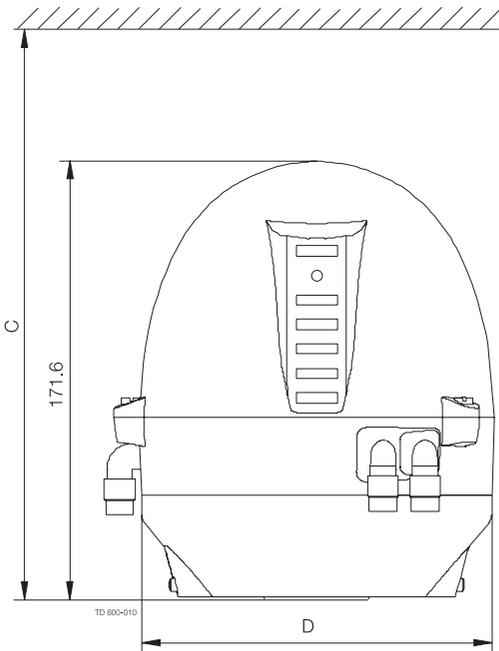
1. Sensor unit
2. Light guide
3. O-ring
4. Base
5. Adapter
6. Shell
7. Terminals
8. Activator stem
9. Cable gland
10. Special X-ring

11. Air fitting
12. Solenoid valve (3/2 or 5/2)
13. Safety valve
14. Solenoid valve (3/2)

Fig. 2. Basic design, ThinkTop®.

Note!

- 1) The ThinkTop® for the SMP-EC valve has a longer activator stem which is going through the shell (see Ordering Leaflet).
- 2) The ThinkTop® for the SRC-LS requires a special magnet. Consult Alfa Laval.



- Note!** This is the basic design. The clearance should be approximately:
- 7.1" dia. x 9.8" (ø180 x 250 mm)
 - (SSV NC, SMP-SC/-BC/-TO, Unique, Koltek MH, SBV, AMP)
 - 7.1" dia. x 12.6" (ø180 x 320 mm) (SSV NO)
 - 7.1" dia. x 11.8" (ø180 x 300 mm) (LKB/LKLA-T)

Fig. 3. Dimensions

Options

- 6.6 ft. cable (6.6 x 0.02"²) {2m cable (2 x 0.5 mm²)} with ASI flat cable connector (Hirschmann).

Accessories

- IR keypad.
- External indication bracket for SMP-SC.

Note!

The ThinkTop® has Patented Sensor System, Registered Design and Registered Trademark.

Ordering

Please state the following when ordering:

- AS-Interface 29.5 - 31.6 VDC.
- Number of solenoids (0-3).
- Type of valve (3/2, 5/2).
- Air connection 1/4" or 6mm
- Please state if for series 700 valves.
- For ThinkTop when used on SSV-LS Stop valve size 2½" - 4" / DN 65 - 100: Special indication pin 9612-6370-01.

